

LAMPIRAN

Lampiran 1. Penyederhanaan Persamaan (3.17)

$$m'(y_n) = f[y_n, z_n] - \frac{f(z_n)f[x_n, y_n, z_n]}{f[z_n, x_n]} + f(y_n) \frac{f[x_n, y_n, z_n]}{f[x_n, z_n]}. \quad (\text{L.1})$$

Persamaan (L.1) disederhanakan sehingga didapat

$$m'(y_n) = \frac{f[y_n, z_n]f[x_n, z_n] + f[x_n, y_n, z_n](f(y_n) - f(z_n))}{f[x_n, z_n]}. \quad (\text{L.2})$$

Dari persamaan (L.2), fungsi $f[x_n, y_n, z_n]$ disederhanakan sehingga ditulis

$$\begin{aligned} f[x_n, y_n, z_n] &= \frac{f[x_n, y_n] - f[y_n, z_n]}{x_n - z_n} = \frac{\frac{f(x_n) - f(y_n)}{x_n - y_n} - \frac{f(y_n) - f(z_n)}{y_n - z_n}}{x_n - z_n}, \\ &= \frac{(f(x_n) - f(y_n))(y_n - z_n) - (f(y_n) - f(z_n))(x_n - y_n)}{(x_n - y_n)(x_n - z_n)(y_n - z_n)}, \end{aligned}$$

$$\begin{aligned}
&= \frac{f(x_n)(y_n) - f(x_n)(z_n) - f(y_n)(y_n) + f(y_n)(z_n) - f(y_n)(x_n)}{(x_n - y_n)(x_n - z_n)(y_n - z_n)} \\
&\quad + \frac{f(y_n)(y_n) + f(z_n)(x_n) - f(z_n)(y_n) + (f(x_n)(x_n) - f(x_n)(x_n))}{(x_n - y_n)(x_n - z_n)(y_n - z_n)}, \\
&= \frac{(f(x_n)(x_n) - f(x_n)(z_n) - f(y_n)(x_n) + f(y_n)(z_n))}{(x_n - y_n)(x_n - z_n)} \\
&\quad - \frac{(f(x_n)(x_n) - f(x_n)(y_n) - f(x_n)(y_n) + f(x_n)(y_n))}{(x_n - y_n)(x_n - z_n)}, \\
&= \frac{(f(x_n) - f(y_n))(x_n - z_n) - (f(y_n) - f(z_n))(x_n - y_n)}{(x_n - y_n)(x_n - z_n)(y_n - z_n)}, \\
&= \frac{(f(x_n) - f(y_n)) - \frac{f(y_n) - f(z_n)}{(x_n - y_n)}}{(y_n - z_n)}, \\
&= \frac{f[x_n, y_n] - f[x_n, z_n]}{y_n - z_n}.
\end{aligned}$$

(L.3)

Hasil penyederhanaan yang terdapat pada persamaan (L.3) disubstitusikan ke persamaan (L.2) lalu disederhanakan lagi sehingga dapat ditulis

$$\begin{aligned}
 m'(y_n) &= \frac{f[y_n, z_n]f[x_n, z_n] + \left(\frac{f[x_n, y_n] - f[x_n, z_n]}{y_n - z_n} \right) (f(y_n) - f(z_n))}{f[x_n, z_n]}, \\
 &= \frac{f[y_n, z_n]f[x_n, z_n] + (f[x_n, y_n] - f[x_n, z_n]) \left(\frac{f(y_n) - f(z_n)}{y_n - z_n} \right)}{f[x_n, z_n]}, \\
 &= \frac{f[y_n, z_n]f[x_n, z_n] + (f[x_n, y_n] - f[x_n, z_n]) \left(\frac{f(y_n) - f(z_n)}{y_n - z_n} \right)}{f[x_n, z_n]}, \\
 &= \frac{f[y_n, z_n]f[x_n, z_n] + (f[x_n, y_n] - f[x_n, z_n]) (f[y_n, z_n])}{f[x_n, z_n]}, \\
 &= \frac{f[y_n, z_n]f[x_n, z_n] + f[x_n, y_n]f[y_n, z_n] - f[y_n, z_n]f[x_n, z_n]}{f[x_n, z_n]}, \\
 &= \frac{f[x_n, y_n]f[y_n, z_n]}{f[x_n, z_n]}
 \end{aligned} \tag{L.4}$$

Lampiran 2. Hasil Perhitungan Beda Terbagi Persamaan (3.20)

$$\begin{aligned}
 f[x_n, z_n] &= \frac{f(x_n) - f(z_n)}{x_n - z_n} \\
 &= c_1 + (c_2 c_1 + 2c_2)e_n + \left(\frac{c_3}{c_1} + c_3 c_1^2 + 3c_3 c_1 + c_2^2 + 2c_3\right)e_n^2 \\
 &\quad + \left(\frac{-c_3 c_2 + 2c_1 c_2 c_3 + c_1 c_3 + 6c_4 c_1^2 + 4c_1 c_4 + 4c_1^3 c_4}{c_1} + \frac{-c_3 + c_4 c_1^4 + 2c_1^2 c_2 c_3}{c_1^2} - \frac{c_2 c_3}{c_1^2}\right)e_n^3 \\
 &\quad + \left(\frac{c_2 c_3 - c_1 c_2 c_3 - 4c_2 c_4 c_1^3 - c_2 c_4 c_1^4 - 2c_2^2 c_3 c_1^2 + c_3 c_2^2}{c_1^2} \right. \\
 &\quad \left. + \frac{-2c_1 c_3^2 - 3c_1^2 c_3^2 - c_3^2 - 6c_1 c_2 c_4 - 3c_1 c_2^2 c_3 - c_1^3 c_3^2 - 7c_1^2 c_2 c_4}{c_1^2} + \frac{c_2^2 c_3}{c_1^3}\right)e_n^4 + O(e_n^5).
 \end{aligned}
 \tag{L.5}$$

$$\begin{aligned}
 f[x_n, y_n] &= \frac{f(x_n) - f(y_n)}{x_n - y_n} \\
 &= c_1 + c_2 e_n + \frac{(c_1^2 c_2^2 + c_1^3 c_2^2)}{c_1^3} e_n^2
 \end{aligned}$$

$$\begin{aligned}
& + \frac{c_2 c_1^3 c_3 + 2c_3 c_1 c_2 + 3c_2 c_3 c_1^2 - 2c_1 c_2^3 + c_4 c_1^2}{c_1^2} + \frac{-2c_2^3 + c_1^2 c_3 - c_1^2 c_2^3}{c_1^2} e_n^3 \\
& + (-3c_2^4 c_1^3 - c_2^4 c_1^4 + 4c_2 c_4 c_1^3 + c_2 c_3 c_1^3 - 3c_1^2 c_2^4 - 3c_1^3 c_3 c_2^2 + c_3 c_1^4 c_2^2 \\
& + 7c_2 c_4 c_1^4 + 4c_2 c_4 c_1^5 + c_1^6 c_2 c_4 + c_2 c_1^4 c_3) e_n^4 + O(e_n^5).
\end{aligned}$$

(L.6)

$$\begin{aligned}
f[y_n, z_n] &= \frac{f(y_n) - f(z_n)}{y_n - z_n} \\
&= c_1 + c_2(1 + c_1)e_n + \frac{c_1 c_3 + c_2^2 + 2c_1^2 c_3 + 3c_1 c_2^2 + 3c_3 c_1^3 + 2c_2^2 c_1^2 + c_1^4 c_3}{c_1(1 + c_1)} e_n^2 \\
&\quad + \left(\frac{c_4 c_1^2 + 11c_1^2 c_2 c_3 + 3c_1 c_2 c_3 - 2c_2^3 - 6c_2^3 c_1 + 5c_4 c_1^3 + c_1^3 c_3}{c_1^2(1 + c_1)^2} \right. \\
&\quad \left. + \frac{10c_4 c_1^4 + c_1^4 c_3 - 7c_1^2 c_2^3 + 10c_4 c_1^5 - 4c_1^3 c_2^3 + 5c_1^6 c_4 - c_2^3 c_1^4}{c_1^2(1 + c_1)^2} \right) e_n^3
\end{aligned}$$

$$\begin{aligned}
& + \frac{c_1^7 c_4 + 14c_1^4 c_2 c_3 + 19c_1^3 c_2 c_3 + 4c_1^5 c_2 c_3}{c_1^2(1+c_1)^2} e_n^3. \\
& + \frac{-39c_1^4 c_2^2 c_3 - 49c_1^3 c_2^2 c_3 + c_1^7 c_2 c_4 + 41c_2 c_4 c_1^4 - 17c_1^5 c_2^2 c_3}{c_1^2(1+c_1)^3} \\
& + \frac{-3c_1^6 c_2^2 c_3 + 8c_2 c_4 c_1^6 + 25c_1^5 c_2 c_4 + 4c_1^4 c_1^4 + 7c_1^3 c_2^4 + 6c_1^6 c_3^2}{c_1^2(1+c_1)^3} \\
& + \frac{15c_1^5 c_3^2 + 21c_1^4 c_3^2 + c_1^5 c_2^4 + c_1^7 c_3^2 + c_2^4 + 4c_2^4 c_1 + 17c_1^3 c_3^2}{c_1^2(1+c_1)^3} \\
& + \frac{8c_1^2 c_3^2 + 2c_3^2 c_1 + 7c_1^2 c_2^4 + c_1^3 c_2 c_3 + c_1^2 c_2 c_3 - 18c_2^2 c_1 c_3}{c_1^2(1+c_1)^3} \\
& + \frac{-4c_2^2 c_3 + 4c_1 c_2 c_4 - 37c_3 c_1^2 c_2^2 + 38c_1^3 c_2 c_4 + 19c_2 c_4 c_1^2}{c_1^2(1+c_1)^3} e_n^4 + O(e_n^5).
\end{aligned}$$

(L.7)

Lampiran 3. Hasil Perhitungan Parameter a_0 , a_1 , b_1 , dan Jumlah dari $a_1 - a_0b_1$ Terhadap Persamaan (3.51)

$$\begin{aligned}
 b_1 = & \frac{-(c_1^4 c_2 + c_2 c_1 + 3c_1^2 c_2 + 3c_2 c_1^3)}{(1 + c_1)^3} - \left(\frac{(5c_3 c_1^6 + c_1^7 c_3 + 4c_3 c_1^3) + c_3 c_1^2 + 7c_2^2 c_1^3 + 5c_2^2 c_1^5}{(1 + c_1)^3 c_1^2} \right) \\
 & + \frac{9c_2^2 c_1^4 + 8c_1^4 c_3 + 9c_1^5 c_3 + 2c_2^2 c_1^2 + c_1^6 c_2^2}{(1 + c_1)^3 c_1^2} e_n - \left(\frac{27c_1^4 c_2 c_3 + 19c_1^6 c_4 + 43c_3 c_1^5 c_2 + 35c_3 c_1^6 c_2}{(1 + c_1)^3 c_1^3} \right) \\
 & + \frac{14c_1^7 c_2 c_3 - c_3 c_1^3 + 3c_4 c_1^4 + 3c_2^3 c_1^5 + 2c_1^8 c_3 c_2 + 15c_4 c_1^7 + 6c_4 c_1^8 + c_2^3 c_1^3 - c_1^5 c_3 - 2c_1^4 c_3}{(1 + c_1)^3 c_1^3} \\
 & + \frac{12c_4 c_1^5 + c_3 c_1^2 c_2 + 8c_3 c_1^3 c_2 + c_2^3 c_1^6 + c_1^9 c_4}{(1 + c_1)^3 c_1^3} e_n - \left(\frac{-3c_1^4 c_2 c_3 - 2c_3 c_1^5 c_2 + 75c_1^6 c_2 c_4}{(1 + c_1)^3 c_1^4} \right) \\
 & + \frac{79c_1^7 c_2 c_4 + 22c_1^5 c_3 c_2^2 - 2c_1^4 c_2 h_4 - 6c_1^5 c_2 h_4 + c_1^4 c_3 c_2^2 + 32c_2^2 c_3 c_1^6 + 19c_2^2 c_1^7 c_3 + 47c_2 c_4 c_1^8}{(1 + c_1)^3 c_1^4} \\
 & + \frac{27c_1^8 c_3^2 + 49c_1^7 c_3^2 + 8c_1^9 c_3^2 - 6c_1^6 c_2 h_4 + 4c_1^8 c_2^2 c_3 + 15c_1^9 c_2 c_4 - c_3 c_1^3 c_2 + 38c_2 c_4 c_1^5}{(1 + c_1)^3 c_1^4} \\
 & + \frac{-c_3 c_1^2 c_2^2 + 8c_2 c_4 c_1^4 - 4c_3 c_1^3 c_2^2 + 12c_3^2 c_1^4 + 2c_3^2 c_1^3 - 2c_1^7 c_2 h_4 + 2c_1^{10} c_2 c_4 + c_1^{10} c_3^2}{(1 + c_1)^3 c_1^4}
 \end{aligned}$$

$$\begin{aligned}
& + \frac{+2c_3^2c_1^3 - 2c_1^7c_2h_4 + 2c_1^{10}c_2c_4 + c_1^{10}c_3^2 + 51c_1^6c_3^2 + 32c_1^5c_3^2}{(1+c_1)^3c_1^4}e_n^3 - \frac{2c_1^5c_3c_2^2 + 2c_1^4c_3c_2^2}{c_1^5(1+c_1)^3} \\
& + \frac{2c_2^2c_3c_1^6 + c_2^2c_1^7c_3 + 68c_4c_1^9c_2^2 - 16c_2^3c_3c_1^3 + c_2^3c_3c_1^2 - 86c_2^3c_3c_1^4 - 174c_2^3c_3c_1^5}{c_1^5(1+c_1)^3} \\
& + \frac{-198c_2^3c_3c_1^6 - 5c_3^2c_2c_1^4 - 3c_3^2c_2c_1^3 + 20c_2^2c_2c_1^5 + 85c_3^2c_2c_1^6 + 137c_3^2c_2c_1^7 + 24c_1^5c_3c_4}{c_1^5(1+c_1)^3} \\
& + \frac{3c_4c_3c_1^4 + 8c_2^2c_4c_1^4 + 85c_4c_3c_1^6 + 49c_4c_1^5c_2^2 + 169c_4c_3c_1^7 + 125c_2^2c_4c_1^6 + 204c_4c_3c_1^8}{c_1^5(1+c_1)^3} \\
& + \frac{173c_4c_1^7c_2^2 - 146c_3c_1^7c_2^3 - 72c_3c_1^8c_2^3 + 116c_2c_1^8c_3^2 + 53c_2c_1^9c_3^2 + 153c_4c_3c_1^9}{c_1^5(1+c_1)^3} \\
& + \frac{141c_4c_1^8c_2^2 + 70c_4c_3c_1^{10} + 8c_2^5c_1^2 + 36c_2^5c_1^3 + 69c_2^5c_1^4 + 75c_2^5c_1^5 + 52c_2^5c_1^6 + 24c_2^5c_1^7}{c_1^5(1+c_1)^3} \\
& + \frac{-c_2^8c_3^2 - 5c_1^7c_3^2 - 3c_2^3c_3c_1^{10} + 12c_3^3c_2c_1^{10} + 18c_2^2c_4c_1^{10} + 2c_4c_3c_1^{12} + c_1^9c_2^5}{c_1^5(1+c_1)^3} \\
& + \frac{-12c_1^6c_2^2h_4 - 8c_1^7c_2^2h_4 + c_3^2c_2c_1^{11} - 2c_1^8c_2^2h_4 + 2c_1^{11}c_2^2c_4 - 8c_1^5c_2^2h_4 - 2c_1^4c_2^2h_4}{c_1^5(1+c_1)^3}
\end{aligned}$$

$$+ \frac{c_1^3 c_2^2 c_3 - 2c_3^2 c_1^4 + 7c_1^8 c_2^5 - 22c_1^9 c_2^3 c_3 + 18c_4 c_3 c_1^{11} - 9c_1^6 c_3^2 - 7c_1^5 c_3^2}{c_1^5 (1 + c_1)^3} e_n^4 + O(e_n^5).$$

(L.8)

$$a_0 = c_1 h_4 e_n^4 + c_1 h_5 e_n^5 + c_1 h_6 e_n^6 + c_1 h_7 e_n^7 + (c_2 h_4^2 + c_1 h_8) e_n^8 + O(e_n^9).$$

(L.9)

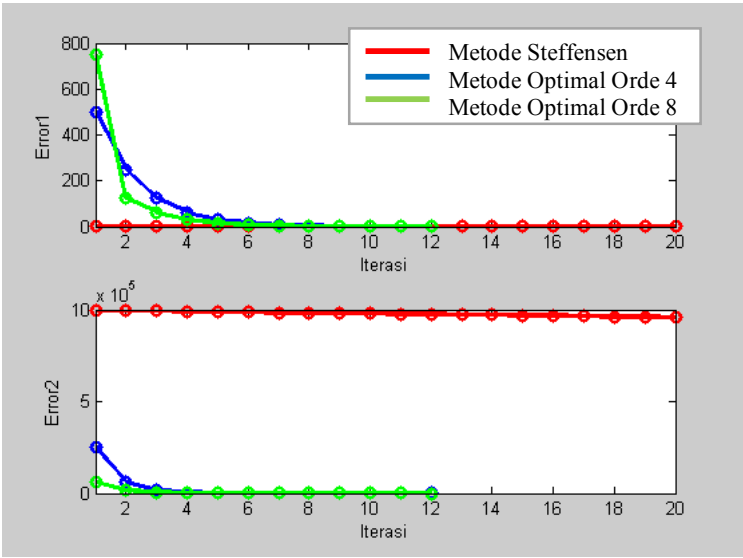
$$a_1 = c_1 + \frac{c_1^3 c_2 h_4 + c_1 c_2 h_4 - c_3^2 - 2c_3^2 c_1 - c_3^2 c_1^2 + c_4 + 2c_1 c_4 + c_4 c_1^2 + c_1 h_4}{c_1} e_n^4 + O(e_n^5).$$

(L.10)

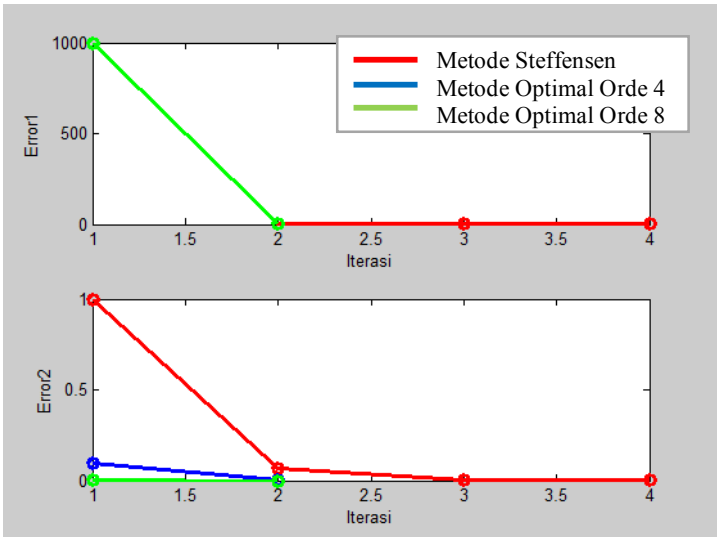
Selanjutnya, hasil a_0 pada persamaan (L.9), hasil b_1 pada persamaan (L.8), dan hasil a_1 pada persamaan (L.10) dilakukan perhitungan $a_1 - a_0 b_1$ sehingga didapat

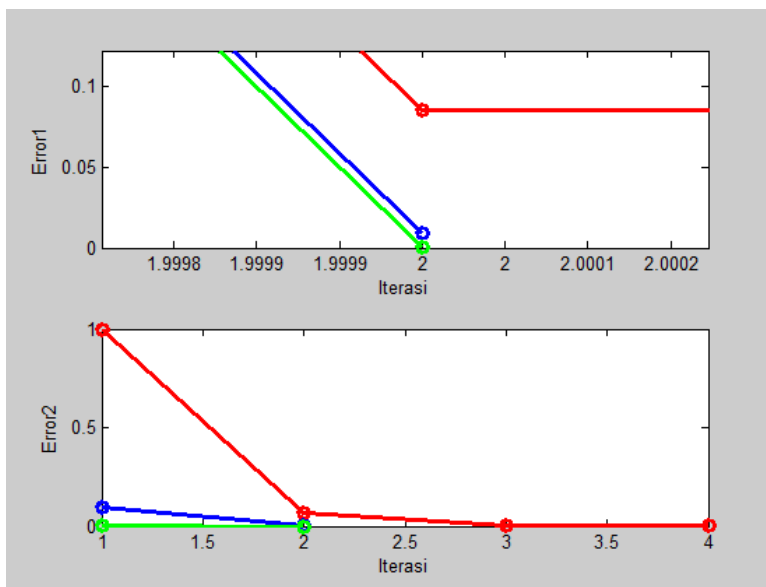
$$a_1 - a_0 b_1 = c_1 - \frac{c_1 c_2 h_4 + c_3^2 + 2c_3^2 c_1 + c_3^2 c_1^2 - c_4 - 2c_1 c_4 - c_4 c_1^2 - c_1 h_4}{c_1} e_n^4 + O(e_n^5).$$

Lampiran 4. Grafik Fungsi $f(x)$ Metode Steffensen, Metode Optimal Orde 4, dan Metode Optimal Orde 8

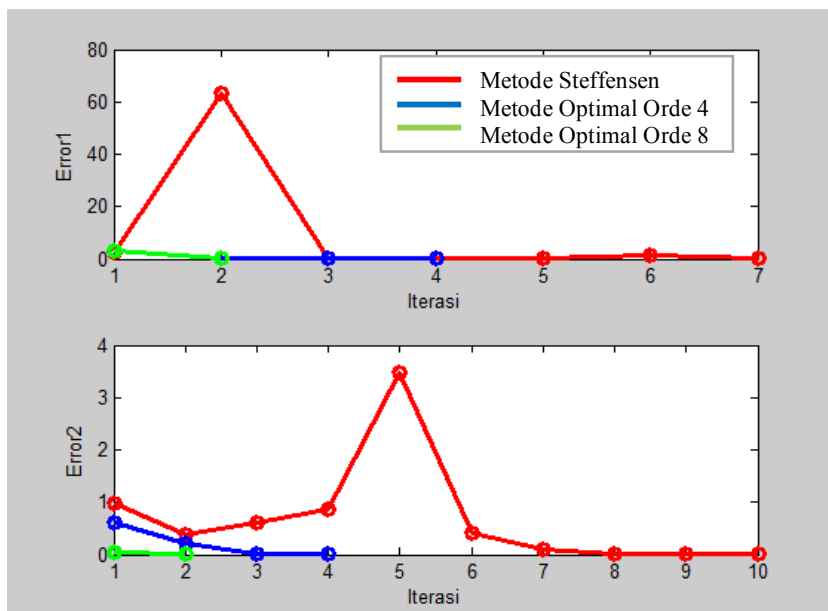


Lampiran 5. Grafik Fungsi $g(x)$ Metode Steffensen, Metode Optimal Orde 4, dan Metode Optimal Orde 8

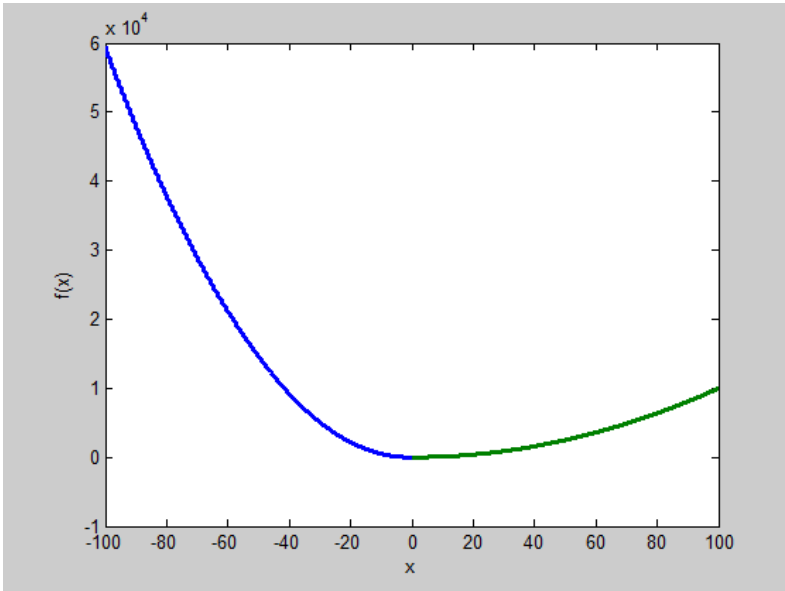




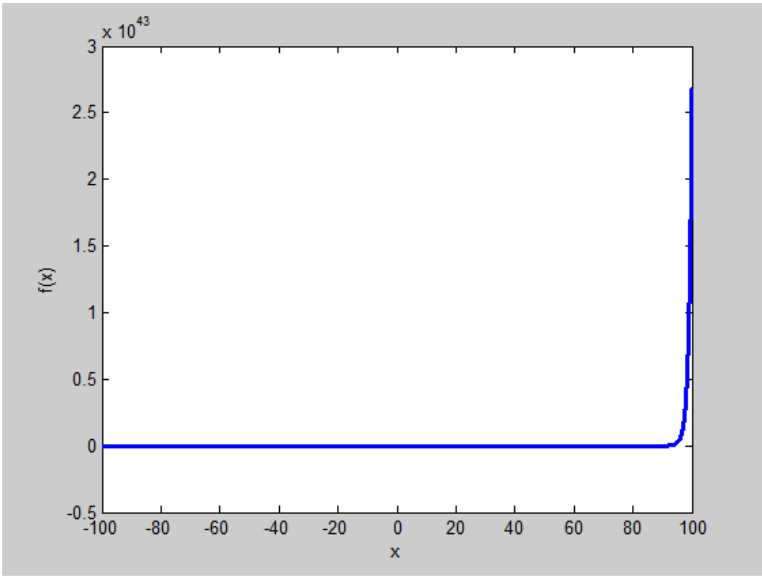
Lampiran 6. Grafik Fungsi $h(x)$ Metode Steffensen, Metode Optimal Orde 4, dan Metode Optimal Orde 8



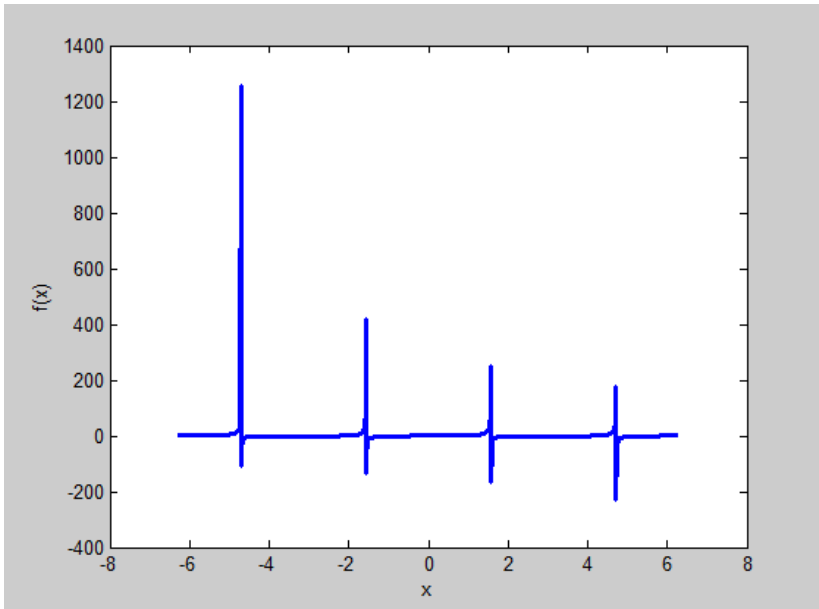
Lampiran 7. Grafik Fungsi $f(x)$



Lampiran 8. Grafik Fungsi $g(x)$



Lampiran 9. Grafik Fungsi $h(x)$



Lampiran 10. Program Matlab Metode Steffensen, Metode Optimal Orde 4, dan Metode Optimal Orde 8 untuk Fungsi $f(x)$

```
clc;
clear all;
tic;
x1(1)=5;
fx1(1)=x1(1)*(x1(1)-1);
i=0;
errorel=10;
erroreanl=10;
while errorel>=10^(-8) && erroreanl>=10^(-8)
    i=i+1;
    if x1(i)<0
        z1(i)=x1(i)+fx1(i);
        fz1(i)=6*z1(i)*(z1(i)+1);
        x1(i+1)=x1(i)-(fx1(i)^2)/(fz1(i)-fx1(i));
        fx1(i+1)=6*x1(i+1)*(x1(i+1)+1);
    else
        z1(i)=x1(i)+fx1(i);
```

```

fz1(i)=z1(i)*(z1(i)-1);
x1(i+1)=x1(i)-(fx1(i)^2)/(fz1(i)-fx1(i));
fx1(i+1)=x1(i+1)*(x1(i+1)-1);
end
error1(i)=abs(x1(i+1)-x1(i));
errorel=error1(i);
erroreal(i)=abs(fx1(i+1));
erroreal1=erroreal(i);
end
toc;
tic;
x2(1)=5;
fx2(1)=x2(1)*(x2(1)-1);
j=0;
errore2=10;
erroreal2=10;
while errore2>=10^(-8) && erroreal2>=10^(-8)
j=j+1;
if x2(j)<0
z2(j)=x2(j)+fx2(j);
fz2(j)=6*z2(j)*(z2(j)+1);
y2(j)=x2(j)-(fx2(j)^2)/(fz2(j)-fx2(j));
fy2(j)=6*y2(j)*(y2(j)+1);
fxz2(j)=(fx2(j)-fz2(j))/(x2(j)-z2(j));
fxy2(j)=(fx2(j)-fy2(j))/(x(j)-y2(j));
fyz2(j)=(fy2(j)-fz2(j))/(y2(j)-z2(j));
x2(j+1)=y2(j)-(fy2(j)*fxz2(j))/(fxy2(j)*fyz2(j));
fx2(j+1)=6*x2(j+1)*(x2(j+1)+1);
u(j)=x2(j+1);
fu(j)=6*u(j)*(u(j)+1);
else
z2(j)=x2(j)+fx2(j);
fz2(j)=z2(j)*(z2(j)-1);
y2(j)=x2(j)-(fx2(j)^2)/(fz2(j)-fx2(j));
fy2(j)=y2(j)*(y2(j)-1);
fxz2(j)=(fx2(j)-fz2(j))/(x2(j)-z2(j));
fxy2(j)=(fx2(j)-fy2(j))/(x2(j)-y2(j));
fyz2(j)=(fy2(j)-fz2(j))/(y2(j)-z2(j));
x2(j+1)=y2(j)-(fy2(j)*fxz2(j))/(fxy2(j)*fyz2(j));
fx2(j+1)=x2(j+1)*(x2(j+1)-1);
u(j)=x2(j+1);
fu(j)=u(j)*(u(j)-1);
end
error2(j)=abs(x2(j+1)-x2(j));

```

```

errore2=error2(j);
errorea2(j)=abs(fx2(j+1));
errorean2=errorea2(j);
end
toc;
tic;
x3(1)=5;
fx3(1)=x3(1)*(x3(1)-1);
k=0;
errore3=10;
errorean3=10;
while errore3>=10^(-8) && errorean3>=10^(-8)
k=k+1;
if x3(k)<0
z3(k)=x3(k)+fx3(k);
fz3(k)=6*z3(k)*(z3(k)+1);
y3(k)=x3(k)-(fx3(k)^2)/(fz3(k)-fx3(k));
fy3(k)=6*y3(k)*(y3(k)+1);
fyz3(k)=(fy3(k)-fz3(k))/(y3(k)-z3(k));
fxy3(k)=(fx3(k)-fy3(k))/(x3(k)-y3(k));
fyu3(k)=(fy3(k)-fu(k))/(y3(k)-u(k));
fux3(k)=(fu(k)-fx3(k))/(u(k)-x3(k));
fyux3(k)=(fyu3(k)-fux3(k))/(y3(k)-x3(k));
fyu3(k)=(fy3(k)-fu(k))/(y3(k)-u(k));
fuz3(k)=(fu(k)-fz3(k))/(u(k)-z3(k));
fyuz3(k)=(fyu3(k)-fuz3(k))/(y3(k)-z3(k));
b1(k)=(fyux3(k)-fyuz3(k))/(fyz3(k)-fxy3(k));
a2(k)=fyux3(k)+b1(k)*fyu3(k);
a1(k)=fyu3(k)-a2(k)*(y3(k)-u(k))+fy3(n)*b1(k);
x3(k+1)=u(k)-((fu(k))/(a1(k)-fu(k)*b1(k)));
fx3(k+1)=6*x3(k+1)*(x3(k+1)+1);
else
z3(k)=x3(k)+fx3(k);
fz3(k)=z3(k)*(z3(k)-1);
y3(k)=x3(k)-(fx3(k)^2)/(fz3(k)-fx3(k));
fy3(k)=y3(k)*(y3(k)-1);
fyz3(k)=(fy3(k)-fz3(k))/(y3(k)-z3(k));
fxy3(k)=(fx3(k)-fy3(k))/(x3(k)-y3(k));
fyu3(k)=(fy3(k)-fu(k))/(y3(k)-u(k));
fux3(k)=(fu(k)-fx3(k))/(u(k)-x3(k));
fyux3(k)=(fyu3(k)-fux3(k))/(y3(k)-x3(k));
fyu3(k)=(fy3(k)-fu(k))/(y3(k)-u(k));
fuz3(k)=(fu(k)-fz3(k))/(u(k)-z3(k));
fyuz3(k)=(fyu3(k)-fuz3(k))/(y3(k)-z3(k));

```

```

b1(k)=(fyux3(k)-fyuz3(k))/(fyz3(k)-fxy3(k));
a2(k)=fyux3(k)+b1(k)*fyu3(k);
a1(k)=fyu3(k)-a2(k)*(y3(k)-u(k))+fy3(k)*b1(k);
x3(k+1)=u(k)-((fu(k))/(a1(k)-fu(k)*b1(k)));
fx3(k+1)=x3(k+1)*(x3(k+1)-1);
end
error3(k)=abs(x3(k+1)-x3(k));
errore3=error3(k);
errorea3(k)=abs(fx3(k+1));
errorean3=errorea3(k);
end
toc;
figure
subplot(2,1,1)
plot(1:i,error1(1:i),'-or',1:j,error2(1:j),'-
ob',1:k,error3(1:k),'-og','LineWidth',2.5);
xlabel('Iterasi')
ylabel('Error1')
subplot(2,1,2)
plot(1:i,errorea1(1:i),'-or',1:j,errorea2(1:j),'-
ob',1:k,errorea3(1:k),'-og','LineWidth',2.5);
xlabel('Iterasi')
ylabel('Error2')

```

Lampiran 11. Program Matlab Metode Steffensen, Metode Optimal Orde 4, dan Metode Optimal Orde 8 untuk Fungsi $g(x)$

```

clc;
clear all;
tic;
x1(1)=0.1;
fx1(1)=exp(x1(1))+10*x1(1);
i=0;
errorel=10;
erroreanl=10;
while errorel>=10^(-8) && erroreanl>=10^(-8)
i=i+1;
z1(i)=x1(i)+fx1(i);
fz1(i)=exp(z1(i))+10*z1(i);
x1(i+1)=x1(i)-(fx1(i)^2)/(fz1(i)-fx1(i));
fx1(i+1)=exp(x1(i+1))+10*x1(i+1);
error1(i)=abs(x1(i+1)-x1(i));
errorel=error1(i);

```



```

erroreal(i)=abs(fx1(i+1));
errorean1=erroreal(i);
end
toc;
tic;
x2(1)=0.1;
fx2(1)=exp(x2(1))+10*x2(1);
j=0;
errore2=10;
errorean2=10;
while errore2>=10^(-8) && errorean2>=10^(-8)
j=j+1;
z2(j)=x2(j)+fx2(j);
fz2(j)=exp(z2(j))+10*z2(j);
y2(j)=x2(j)-(fx2(j)^2)/(fz2(j)-fx2(j));
fy2(j)=exp(y2(j))+10*y2(j);
fxz2(j)=(fx2(j)-fz2(j))/(x2(j)-z2(j));
fxy2(j)=(fx2(j)-fy2(j))/(x2(j)-y2(j));
fyz2(j)=(fy2(j)-fz2(j))/(y2(j)-z2(j));
x2(j+1)=y2(j)-(fy2(j)*fxz2(j))/(fxy2(j)*fyz2(j));
fx2(j+1)=exp(x2(j+1))+10*x2(j+1);
error2(j)=abs(x2(j+1)-x2(j));
errore2=error2(j);
errorea2(j)=abs(fx2(j+1));
errorean2=errorea2(j);
end
toc;
tic;
x3(1)=0.1;
fx3(1)=exp(x3(1))+10*x3(1);
k=0;
errore3=10;
errorean3=10;
while errore3>=10^(-8) && errorean3>=10^(-8)
k=k+1;
z3(k)=x3(k)+fx3(k);
fz3(k)=exp(z3(k))+10*z3(k);
y3(k)=x3(k)-(fx3(k)^2)/(fz3(k)-fx3(k));
fy3(k)=exp(y3(k))+10*y3(k);
fxz3(k)=(fx3(k)-fz3(k))/(x3(k)-z3(k));
fxy3(k)=(fx3(k)-fy3(k))/(x3(k)-y3(k));
fyz3(k)=(fy3(k)-fz3(k))/(y3(k)-z3(k));
g(k)=((fy3(k)*fxz3(k))/(fxy3(k)*fyz3(k)));
u(k)=y3(k)-g(k);

```

```

fu(k)=exp(u(k))+10*u(k);
fyz3(k)=(fy3(k)-fz3(k))/(y3(k)-z3(k));
fxy3(k)=(fx3(k)-fy3(k))/(x3(k)-y3(k));
fyu3(k)=(fy3(k)-fu(k))/(y3(k)-u(k));
fux3(k)=(fu(k)-fx3(k))/(u(k)-x3(k));
fyux3(k)=(fyu3(k)-fux3(k))/(y3(k)-x3(k));
fyu3(k)=(fy3(k)-fu(k))/(y3(k)-u(k));
fuz3(k)=(fu(k)-fz3(k))/(u(k)-z3(k));
fyuz3(k)=(fyu3(k)-fuz3(k))/(y3(k)-z3(k));
b1(k)=(fyux3(k)-fyuz3(k))/(fyz3(k)-fxy3(k));
a2(k)=fyux3(k)+b1(k)*fyu3(k);
a1(k)=fyu3(k)-a2(k)*(y3(k)-u(k))+fy3(k)*b1(k);
x3(k+1)=u(k)-((fu(k))/(a1(k)-fu(k)*b1(k)));
fx3(k+1)=exp(x3(k+1))+10*x3(k+1);
error3(k)=abs(x3(k+1)-x3(k));
errore3=error3(k);
errorea3(k)=abs(fx3(k+1));
errorean3=errorea3(k);
end
toc;
figure
subplot(2,1,1)
plot(1:i,error1(1:i),'-or',1:j,error2(1:j),'-
ob',1:k,error3(1:k),'-og','LineWidth',2.5);
xlabel('Iterasi')
ylabel('Error1')
subplot(2,1,2)
plot(1:i,erroreal(1:i),'-or',1:j,errorea2(1:j),'-
ob',1:k,errorea3(1:k),'-og','LineWidth',2.5);
xlabel('Iterasi')
ylabel('Error2')

```

Lampiran 12. Program Matlab Metode Steffensen, Metode Optimal Orde 4, dan Metode Optimal Orde 8 untuk Fungsi $h(x)$

```

clc;
clear all;
tic;
x1(1)=0;
fx1(1)=sin(x1(1))+cos(x1(1))+tan(x1(1));
i=0;
errore1=10;
errorean1=10;

```

```

while errore1>=10(-8) && errorean1>=10(-8)
i=i+1;
z1(i)=x1(i)+fx1(i);
fz1(i)=sin(z1(i))+cos(z1(i))+tan(z1(i));
x1(i+1)=x1(i)-(fx1(i)^2)/(fz1(i)-fx1(i));
fx1(i+1)=sin(x1(i+1))+cos(x1(i+1))+tan(x1(i+1));
error1(i)=abs(x1(i+1)-x1(i));
errorel=error1(i);
erroreal(i)=abs(fx1(i+1));
errorean1=erroreal(i);
end
toc;
tic;
x2(1)=0;
fx2(1)=sin(x2(1))+cos(x2(1))+tan(x2(1));
j=0;
errore2=10;
errorean2=10;
while errore2>=10(-8) && errorean2>=10(-8)
j=j+1;
z2(j)=x2(j)+fx2(j);
fz2(j)=sin(z2(j))+cos(z2(j))+tan(z2(j));
y2(j)=x2(j)-(fx2(j)^2)/(fz2(j)-fx2(j));
fy2(j)=sin(y2(j))+cos(y2(j))+tan(y2(j));
fxz2(j)=(fx2(j)-fz2(j))/(x2(j)-z2(j));
fxy2(j)=(fx2(j)-fy2(j))/(x2(j)-y2(j));
fyz2(j)=(fy2(j)-fz2(j))/(y2(j)-z2(j));
x2(j+1)=y2(j)-(fy2(j)*fxz2(j))/(fxy2(j)*fyz2(j));
fx2(j+1)=sin(x2(j+1))+cos(x2(j+1))+tan(x2(j+1));
error2(j)=abs(x2(j+1)-x2(j));
errore2=error2(j);
errorea2(j)=abs(fx2(j+1));
errorean2=errorea2(j);
end
toc;
tic;
x3(1)=0;
fx3(1)=sin(x3(1))+cos(x3(1))+tan(x3(1));
k=0;
errore3=10;
errorean3=10;
while errore3>=10(-8) && errorean3>=10(-8)
k=k+1;
z3(k)=x3(k)+fx3(k);

```

```

fz3(k)=sin(z3(k))+cos(z3(k))+tan(z3(k));
y3(k)=x3(k)-(((fx3(k))^2)/(fz3(k)-fx3(k)));
fy3(k)=sin(y3(k))+cos(y3(k))+tan(y3(k));
fxz3(k)=(fx3(k)-fz3(k))/(x3(k)-z3(k));
fxy3(k)=(fx3(k)-fy3(k))/(x3(k)-y3(k));
fyz3(k)=(fy3(k)-fz3(k))/(y3(k)-z3(k));
g(k)=((fy3(k)*fxz3(k))/(fxy3(k)*fyz3(k)));
u(k)=y3(k)-g(k);
fu(k)=sin(u(k))+cos(u(k))+tan(u(k));
fyz3(k)=(fy3(k)-fz3(k))/(y3(k)-z3(k));
fxy3(k)=(fx3(k)-fy3(k))/(x3(k)-y3(k));
fyu3(k)=(fy3(k)-fu(k))/(y3(k)-u(k));
fux3(k)=(fu(k)-fx3(k))/(u(k)-x3(k));
fyux3(k)=(fyu3(k)-fux3(k))/(y3(k)-x3(k));
fyu3(k)=(fy3(k)-fu(k))/(y3(k)-u(k));
fuz3(k)=(fu(k)-fz3(k))/(u(k)-z3(k));
fyuz3(k)=(fyu3(k)-fuz3(k))/(y3(k)-z3(k));
b1(k)=(fyux3(k)-fyuz3(k))/(fyz3(k)-fxy3(k));
a2(k)=fyuz3(k)+b1(k)*fyz3(k);
a1(k)=fyu3(k)-a2(k)*(y3(k)-u(k))+fy3(k)*b1(k);
x3(k+1)=u(k)-((fu(k))/(a1(k)-fu(k)*b1(k)));
fx3(k+1)=sin(x3(k+1))+cos(x3(k+1))+tan(x3(k+1));
error3(k)=abs(x3(k+1)-x3(k));
errore3=error3(k);
errorea3(k)=abs(fx3(k+1));
errorean3=errorea3(k);
end
toc;
figure
subplot(2,1,1)
plot(1:i,error1(1:i),'-or',1:j,error2(1:j),'-
ob',1:k,error3(1:k),'-og','LineWidth',2.5);
xlabel('Iterasi')
ylabel('Error1')
subplot(2,1,2)
plot(1:i,errorea1(1:i),'-or',1:j,errorea2(1:j),'-
ob',1:k,errorea3(1:k),'-og','LineWidth',2.5);
xlabel('Iterasi')
ylabel('Error2')

```